

Servo amplifier

mcDSA-E35-EtherCAT

Article number: 1514514

 Certification:  **US** *1
E475093


Picture similar

Technical data

Supply voltages	
Electronic supply voltage Ue*2	18..30 V
Electronic current consumption@ Ue=24V*3	typ. 65 mA
Power supply voltage Up*4	9..60 V
Output current	
Max. output current	80 A
Continuous output current (certified UL)*5	
@Up ≤ 24V	14.5 A
@Up ≤ 60V	12.2 A
Continuous output current (not certified)*6	
@Up ≤ 24V	16 A
@Up ≤ 48V	13 A
PWM	
Output voltage	90% Up
PWM frequency	25, 32*7, 50 kHz
Mechanical	
Size LxWxH	78 x 74 x 49 mm
Weight	141 g
Environment	
Protection class	IP20
Ambient temperature (operation) (certified UL)	-40..40 °C
Ambient temperature (operation) (not certified)	-40..70 °C
Ambient temperature (storage)	-40..85 °C
Rel. humidity (non-condensing)	5..90 %
CAN bus	
Protocol	DS301
Device profile	DS402
Max. baudrate	1 Mbit/s
CAN specification	2.0B
Galvanically isolated	no
Sensor supply (Hall)	
Output voltage	5 V
Max. output current	0.05 A

EtherCAT	
Type	EtherCAT Slave
Physical layer	100 Base-Tx EtherCAT
Bus controller	ET1100
Max. baudrate	100 Mbit/s
Number of ports	2xRJ45 (In,Out)
Protocol	CoE (CANopen over EtherCAT)
Sensor supply (Encoder)	
Output voltage	5 V
Max. output current	0.2 A
Incremental encoder	
Type	incremental
Signals	A,/A,B,/B,Inx,/Inx
Max. frequency (per channel)	500 kHz
Input voltage	0..5 V
Signal type	differential, open collector, single ended
Hall sensors	
Signals	H1,H2,H3
Max. frequency (per channel)	10 kHz
Input voltage	0..5 V
Signal type	open collector, single ended
Digital inputs	
Number - digital inputs	8 (Din0..7)
Low voltage	0..5 V
High voltage	8..30 V
Digital outputs	
Number	3 (Dout0..2)
Continuous output current (certified UL)	1 A
Continuous output current (not certified)	1.5 A
Load Dout0..1	resistive, low inductive
Load Dout2	resistive, inductive
Output voltage	Electronic supply voltage Ue
Signal type	positive switching
Analog inputs	
Number	1 (Ain0)
Signal type - Ain	+/- 10 V, 12 Bit, differential

*1 The certified performance data must be observed (see UL Instruction Note)

*2 No reverse polarity protection, the destruction limit is at overvoltage of $\geq 33V$ or short-term peak voltage of $37V < 1s$

*3 power amplifier switched off, 5V output (sensor supply) is free

*4 No reverse polarity protection, the destruction limit is at overvoltage of $\geq 80V$ *5 connector cable with max. possible cable cross-section, PWM frequency 32 kHz (asymmetrical), ambient temperature 40 °C, I/O's and 5V output active, RMS current: 14.5 A \rightarrow 12 Aeff, 12.2 A \rightarrow 10 Aeff*6 connector cable with max. possible cable cross-section, PWM frequency 32 kHz (asymmetrical), ambient temperature 40 °C, I/O's and 5V output free, RMS current: 16 A \rightarrow 13 Aeff, 13 A \rightarrow 10.6 Aeff

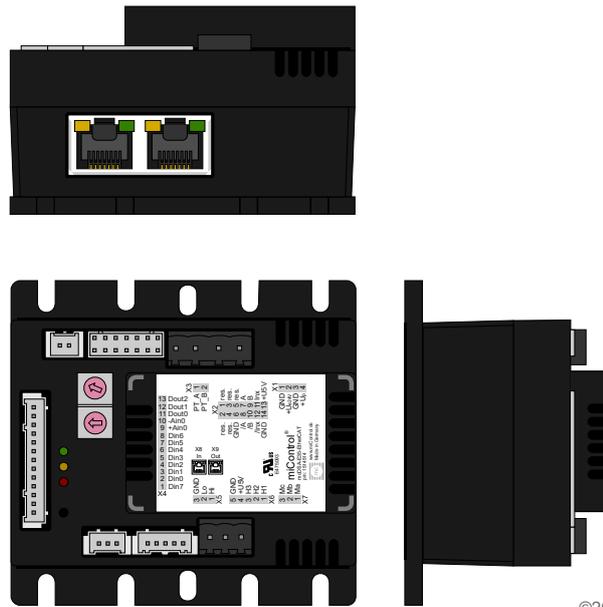
no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

*7 default value

Additional technical data are available in mcManual.


 miControl® GmbH
 Chausseestraße 34
 14979 Großbeeren (bei Berlin)

Scheme



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Terminal assignment

X1 Supply		
1	GND	Ground for electronic supply voltage
2	+Ue24V	Electronic supply voltage
3	GND	Ground for power supply voltage
4	+Up	Power supply voltage
X2 Encoder		
1	res.	Reserved
2	res.	Reserved
3	res.	Reserved
4	res.	Reserved
5	res.	Reserved
6	GND	Ground for sensor supply Notice: don't connect with system GND
7	A	Inc. encoder, A channel
8	/A	Inc. encoder, A channel inverted
9	B	Inc. encoder, B channel
10	/B	Inc. encoder, B channel inverted
11	Inx	Inc. encoder, index channel
12	/Inx	Inc. encoder, index channel inverted
13	+U5V	5V output voltage for sensor supply Sensors: encoder, SSI
14	GND	Ground for sensor supply Notice: don't connect with system GND
X3 PT1000		
1	PT_A	PT_A
2	PT_B	PT_B
X4 I/O's		
1	Din7	Digital input 7
2	Din0	Digital input 0
3	Din1	Digital input 1
4	Din2	Digital input 2
5	Din3	Digital input 3
6	Din4	Digital input 4
7	Din5	Digital input 5
8	Din6	Digital input 6
9	+Ain0	Analog input 0, plus
10	-Ain0	Analog input 0, minus
11	Dout0	Digital output 0
12	Dout1	Digital output 1
13	Dout2	Digital output 2

X5 CAN bus		
1	CAN Hi	CAN High
2	CAN Lo	CAN Low
3	CAN GND	CAN Ground
X6 Hall encoder		
1	H1	Hall sensor 1
2	H2	Hall sensor 2
3	H3	Hall sensor 3
4	+U5V	5V output voltage for sensor supply Sensors: hall
5	GND	Ground for sensor supply Notice: don't connect with system GND
X7 Motor		
1	Ma	Motor phase A
2	Mb	Motor phase B
3	Mc	Motor phase C
X8 EtherCAT - In port		
-	In	In
X9 EtherCAT - Out port		
-	Out	Out