

Servo amplifier

mcDSA-F37-PROFINET-HC

Article number: 1514239

Certification:



Picture similar

Technical data

| Supply voltages | |
|---|------------------------|
| Electronic supply voltage Ue*2 | 18..30 V |
| Electronic current consumption@ Ue=24V*3 | typ. 65 mA |
| Power supply voltage Up*4 | 9..60 V |
| Output current | |
| Max. output current | 120 A |
| Continuous output current (certified UL/CE)*5 | |
| @Up ≤ 24V | 26 A |
| @Up ≤ 60V | 26 A |
| Continuous output current (not certified)*6 | |
| @Up ≤ 24V | 34 A |
| @Up ≤ 48V | 34 A |
| PWM | |
| PWM frequency | 32 kHz |
| Commutation type | Field Oriented Control |
| Mechanical | |
| Size LxWxH | 87 x 74 x 49 mm |
| Weight | 226 g |
| Environment | |
| Protection class | IP20 |
| Installation requirements *7 | IP54 |
| Ambient temperature (operation) (certified UL) | -40..50 °C |
| Ambient temperature (operation) (certified CE) | -40..55 °C |
| Ambient temperature (operation) (not certified) | -40..70 °C |
| Ambient temperature (storage) | -40..85 °C |
| Rel. humidity (non-condensing) | 5..90 % |
| CAN bus | |
| Protocol | DS301 |
| Device profile | DS402 |
| Max. baudrate | 1 Mbit/s |
| CAN specification | 2.0B |
| Galvanically isolated | no |
| RS485 | |
| Type | 2-Wire EIA-485 |
| Signals | DATA,/DATA,CLK,/CLK |
| Functional safety | |
| Safety function refer safety manual | Safe Torque Off (STO) |
| Safety Integrity Level (SIL) | up to SIL 3 |
| Performance Level (PL) | up to PL e |

| PROFINET | |
|---|-----------------------------------|
| Type | Slave |
| Physical layer | 100 Base-Tx |
| Max. baudrate | 100 Mbit/s |
| Number of ports | 2xRJ45 (PORT1, PORT2) |
| Sensor supply (Hall) | |
| Output voltage | 5 V |
| Max. output current | 0.05 A |
| Sensor supply (Encoder/SSI) | |
| Output voltage | 5 V |
| Max. output current | 0.2 A |
| Sensor supply (Hiperface) | |
| Output voltage | 10 V |
| Max. output current | 0.25 A |
| Encoder | |
| Type | sin / cos |
| Signals | +Sin,-Sin,+Cos,-Cos |
| Resolution | 13 bit per sine period |
| Input voltage | 1 V peak-peak, differential |
| Signal type | sine/cosine, analog, differential |
| Hall sensors | |
| Signals | H1,H2,H3 |
| Max. frequency (per channel) | 10 kHz |
| Input voltage | 0..5 V |
| Signal type | open collector, single ended |
| Digital inputs | |
| Number - digital inputs | 6 (Din0..5) |
| Low voltage | 0..5 V |
| High voltage | 8..30 V |
| STO channels (ST0-A..B) | |
| Low voltage | 0..5 V |
| High voltage | 8..30 V |
| Digital outputs | |
| Number | 3 (Dout0..2) |
| Continuous output current (certified UL/CE) | 1 A |
| Continuous output current (not certified) | 1.5 A |
| Load Dout0..1 | resistive, low inductive |
| Load Dout2 | resistive, inductive |
| Output voltage | Electronic supply voltage Ue |
| Signal type | positive switching |
| Analog inputs | |
| Number | 1 (Ain0) |
| Signal type - Ain | +/- 10 V, 12 Bit, differential |

*1 The certified performance data must be observed (see UL Instruction Note and Safety Manual (CE))

*2 No reverse polarity protection, the destruction limit is at overvoltage of $\geq 33V$ or short-term peak voltage of $37V < 1s$

*3 power amplifier switched off, 5V output (sensor supply) is free, STO active

*4 No reverse polarity protection, the destruction limit is at overvoltage of $\geq 70V$

*5 connector cable with max. possible cable cross-section, PWM frequency 32 kHz (SVPWM), ambient temperature 50 °C, I/O's and 5V output active, RMS current:

26 A → 18.5 Aeff

*6 connector cable with max. possible cable cross-section, PWM frequency 32 kHz (SVPWM), ambient temperature 40 °C, I/O's and 5V output free, RMS current: 34

A → 24 Aeff

no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

*7 or equivalent protection class (see Safety Manual (CE))

Additional technical data are available in mcManual.

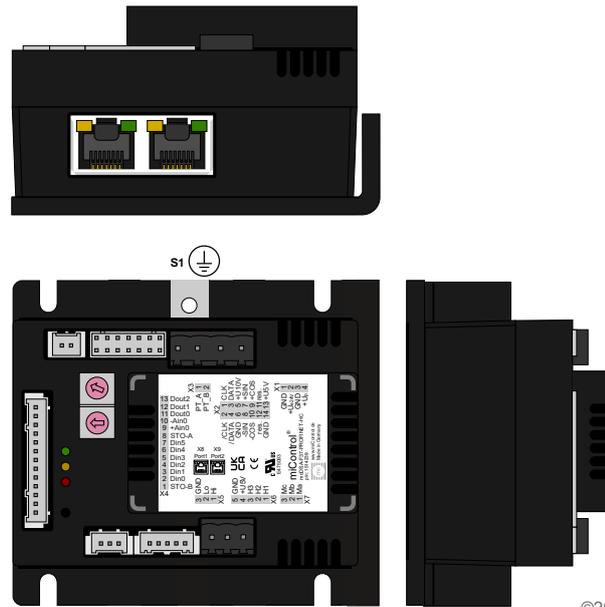


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Scheme



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Terminal assignment

| X1 Supply | | |
|------------|--------|---|
| 1 | GND | Ground for electronic supply voltage |
| 2 | +Ue24V | Electronic supply voltage |
| 3 | GND | Ground for power supply voltage |
| 4 | +Up | Power supply voltage |
| X2 Encoder | | |
| 1 | CLK | SSI clk |
| 2 | /CLK | /SSI clk |
| 3 | DATA | SSI data |
| 4 | /DATA | /SSI data |
| 5 | +U10V | 10V output voltage for sensor supply Sensors: Hiperface |
| 6 | GND | Ground for sensor supply Notice: don't connect with system GND |
| 7 | +SIN | Encoder, plus sine signal |
| 8 | -SIN | Encoder, minus sine signal |
| 9 | +COS | Encoder, plus cosine signal |
| 10 | -COS | Encoder, minus cosine signal |
| 11 | res. | Reserved |
| 12 | res. | Reserved |
| 13 | +U5V | 5V output voltage for sensor supply Sensors: encoder, SSI |
| 14 | GND | Ground for sensor supply Notice: don't connect with system GND |
| X3 PT1000 | | |
| 1 | PT_A | PT_A |
| 2 | PT_B | PT_B |
| X4 I/O's | | |
| 1 | STO-B | STO channel B |
| 2 | Din0 | Digital input 0 |
| 3 | Din1 | Digital input 1 |
| 4 | Din2 | Digital input 2 |
| 5 | Din3 | Digital input 3 |
| 6 | Din4 | Digital input 4 |
| 7 | Din5 | Digital input 5 |
| 8 | STO-A | STO channel A |
| 9 | +Ain0 | Analog input, plus |
| 10 | -Ain0 | Analog input, minus |
| 11 | Dout0 | Digital output 0 |
| 12 | Dout1 | Digital output 1 |
| 13 | Dout2 | Digital output 2 |

| X5 CAN bus | | |
|---------------------|---------|---|
| 1 | CAN Hi | CAN High |
| 2 | CAN Lo | CAN Low |
| 3 | CAN GND | CAN Ground |
| X6 Hall encoder | | |
| 1 | H1 | Hall sensor 1 |
| 2 | H2 | Hall sensor 2 |
| 3 | H3 | Hall sensor 3 |
| 4 | +U5V | 5V output voltage for sensor supply Sensors: hall |
| 5 | GND | Ground for sensor supply Notice: don't connect with system GND |
| X7 Motor | | |
| 1 | Ma | Motor phase A |
| 2 | Mb | Motor phase B |
| 3 | Mc | Motor phase C |
| S1 Screw (M3) | | |
| - | FE | Functional earth |
| X8 PROFINET - PORT1 | | |
| - | PORT1 | PORT1 |
| X9 PROFINET - PORT2 | | |
| - | PORT2 | PORT2 |